



The SAT Problem

Structure through Visualization

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Some Terminology

- A *variable* is a Boolean variable which can be assigned either T or F
- A *literal* is a variable which may be negated ($\neg x$ vs x)

Some Terminology

The SAT Problem

Satisfiable?

More Difficult?

DP (DLL)

Stochastic Search

State Space

Visualizations

Visualizations (2)

Visualizations (3)

References

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- A *variable* is a Boolean variable which can be assigned either T or F
- A *literal* is a variable which may be negated ($\neg x$ vs x)
- We write OR as \vee , AND as \wedge
- Example:

If we let $x = T$, then $\neg x = F$

- Example:

$$(A \vee \neg B \vee C) \wedge (A \vee B \vee \neg C) \wedge (\neg A \vee \neg B \vee C)$$

The SAT Problem

- Can we satisfy k literals in c clauses (CNF)?

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- Can we satisfy k literals in c clauses (CNF)?
 - ▲ If yes, what are the assignments?
 - ▲ If no, exhaustive search needed? ($P \neq NP$)
- Problem is NP-complete (Cook '71)^[1]
- Example:

$$(\neg A \vee B \vee \neg C) \wedge$$

$$(\neg A \vee \neg B \vee D) \wedge (\neg D)$$

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Some solutions:

$$A=F, B=T, C=F, D=F$$

$$A=F, B=T, C=T, D=F$$

$$A=T, B=F, C=F, D=F$$

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$$(A \vee \neg B \vee \neg C) \wedge$$

$$(\neg A \vee B \vee D) \wedge$$

$$(\neg A \vee \neg B \vee \neg D)$$

Yes! $A = T, B = T, C = T, D = F$

More Difficult?

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$$(A \vee \neg B \vee \neg C) \wedge$$

$$(\neg A \vee \neg \mathbf{B} \vee D) \wedge \quad \leftarrow B \text{ is now negated}$$

$$(\neg A \vee \neg B \vee \neg D)$$

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$$(\neg A \vee \neg \mathbf{B} \vee D) \wedge \quad \leftarrow B \text{ is now negated}$$

$$(\neg A \vee \neg B \vee \neg D)$$

No solution!

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DP (DLL)

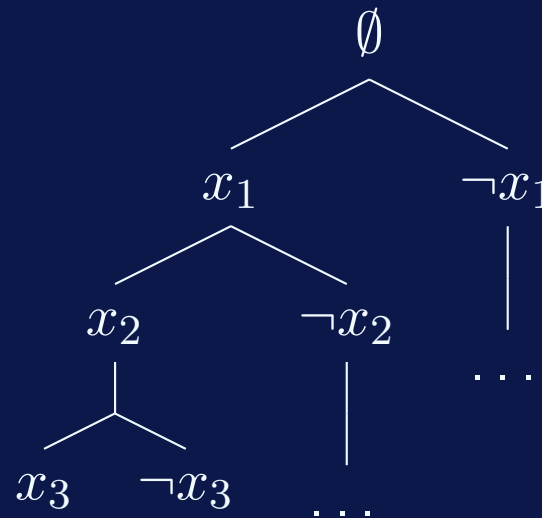
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Algorithm 1 DP Algorithm^[2] ^[3]

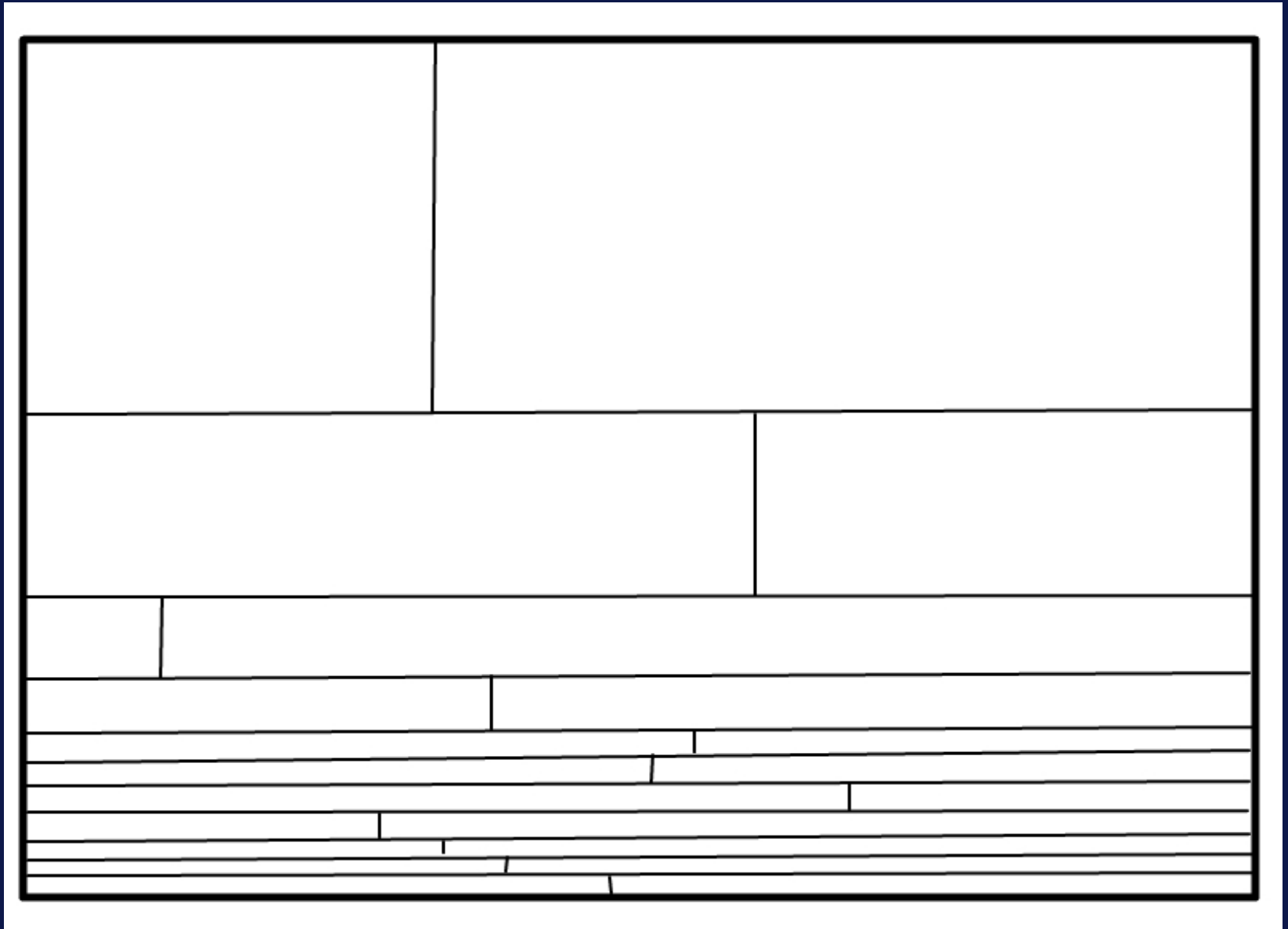
```
1: procedure DP( $c$ )                                ▷ Derive  $\emptyset$  or F from CNF( $c$ )
2:   while  $c \neq \{F\}$  and  $c \neq \emptyset$  do
3:      $\delta \leftarrow \text{SetAtomicLiterals}(c)$ 
4:     if  $|\delta| \leq 1$  return  $c$ 
5:      $\delta \leftarrow \text{SetPureLiterals}(c)$ 
6:     if  $\delta \neq c$  then loop                       ▷ Propagate pure literals
7:        $c \leftarrow \text{SetVar}(x \in \delta, \delta)$ 
8:   end while
9:   return  $c$ 
10: end procedure
```

Stochastic Search

- Randomly assign variables
- Improve working solution
 - ▲ Escape local minima
 - ▲ Avoid full state space
 - ▲ Determine unsat. without exhaustive search



State Space



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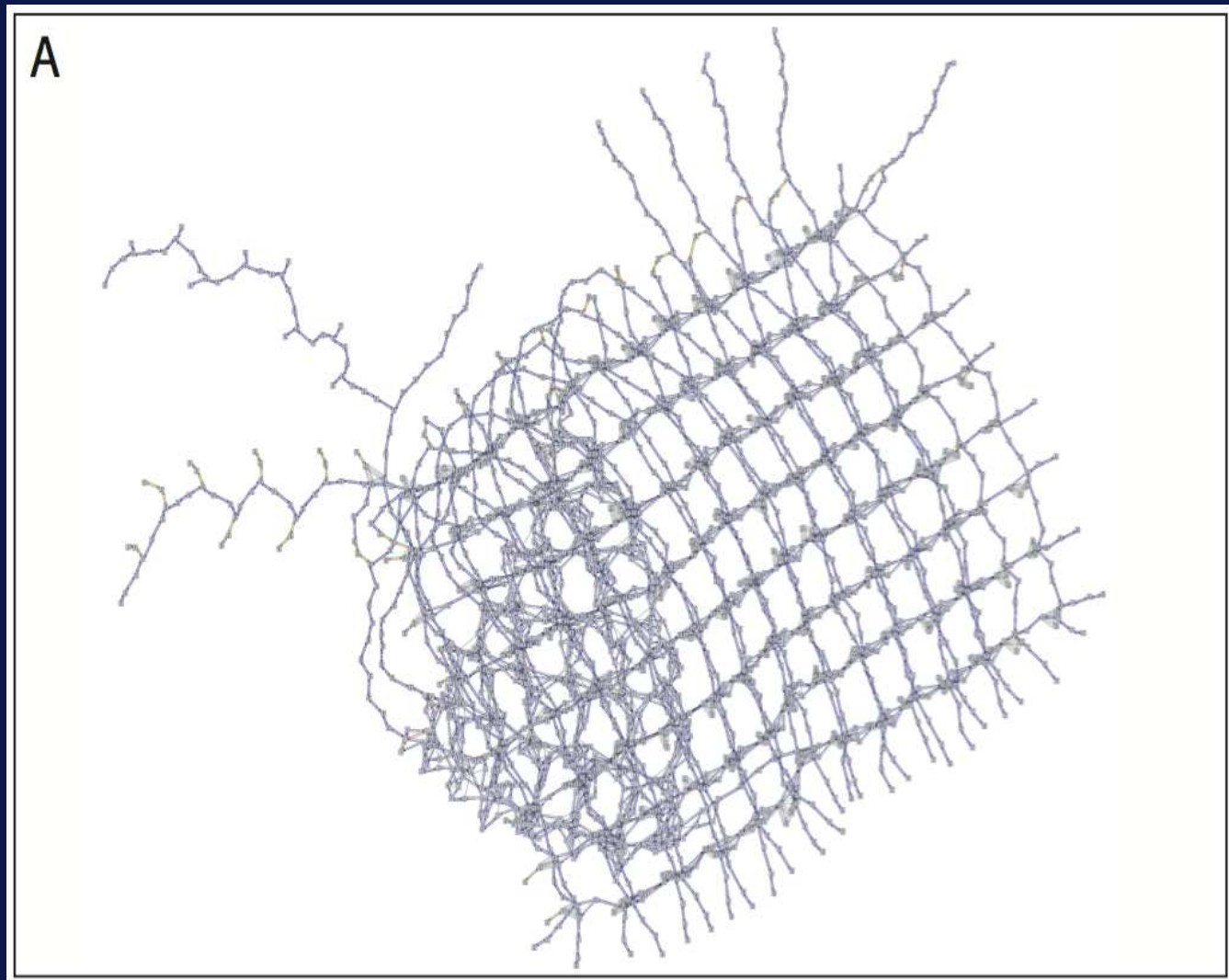


Figure 1: Literal-Based Renderings^[4]

Visualizations (2)

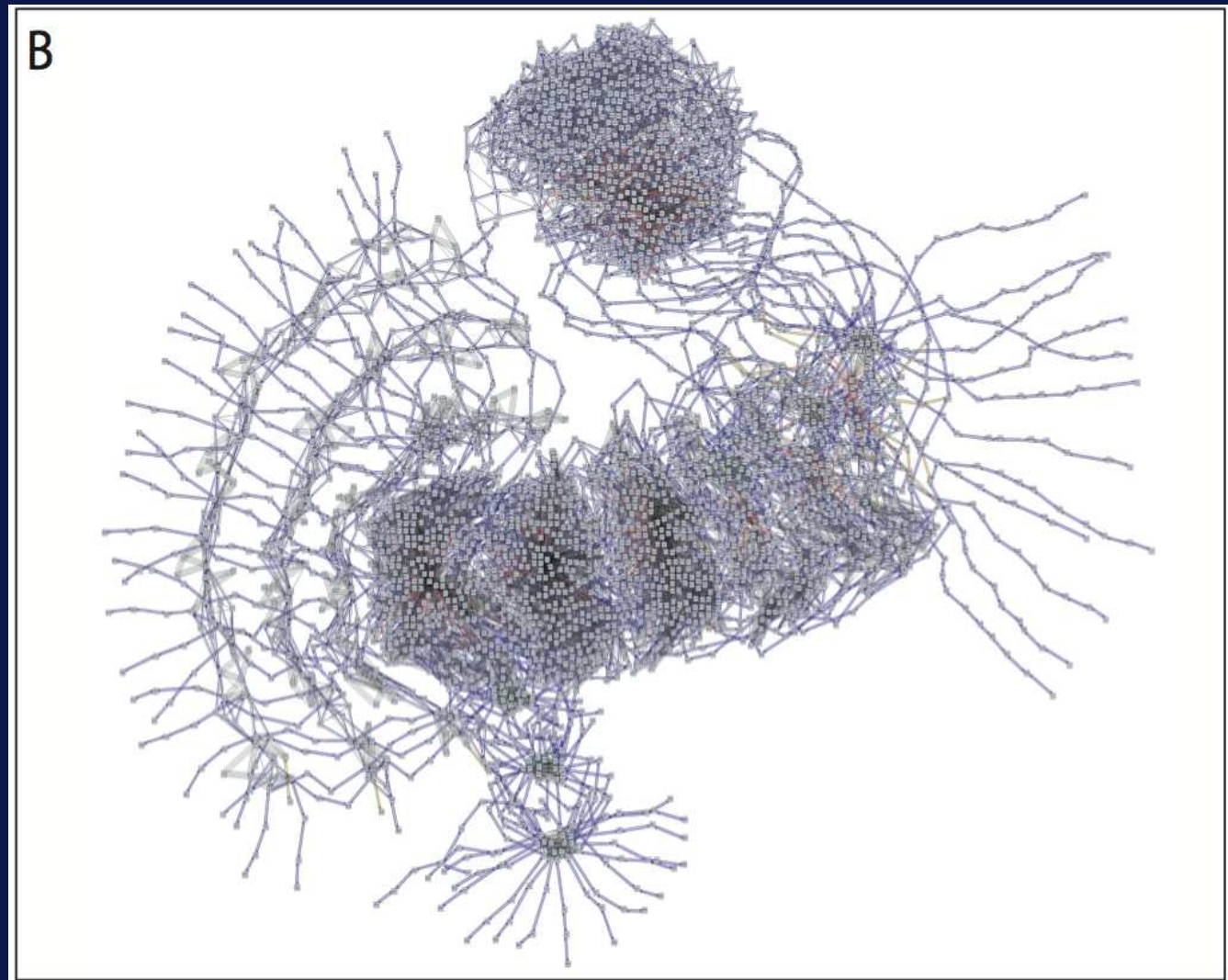


Figure 2: Literal-Based Renderings^[4]

Visualizations (3)

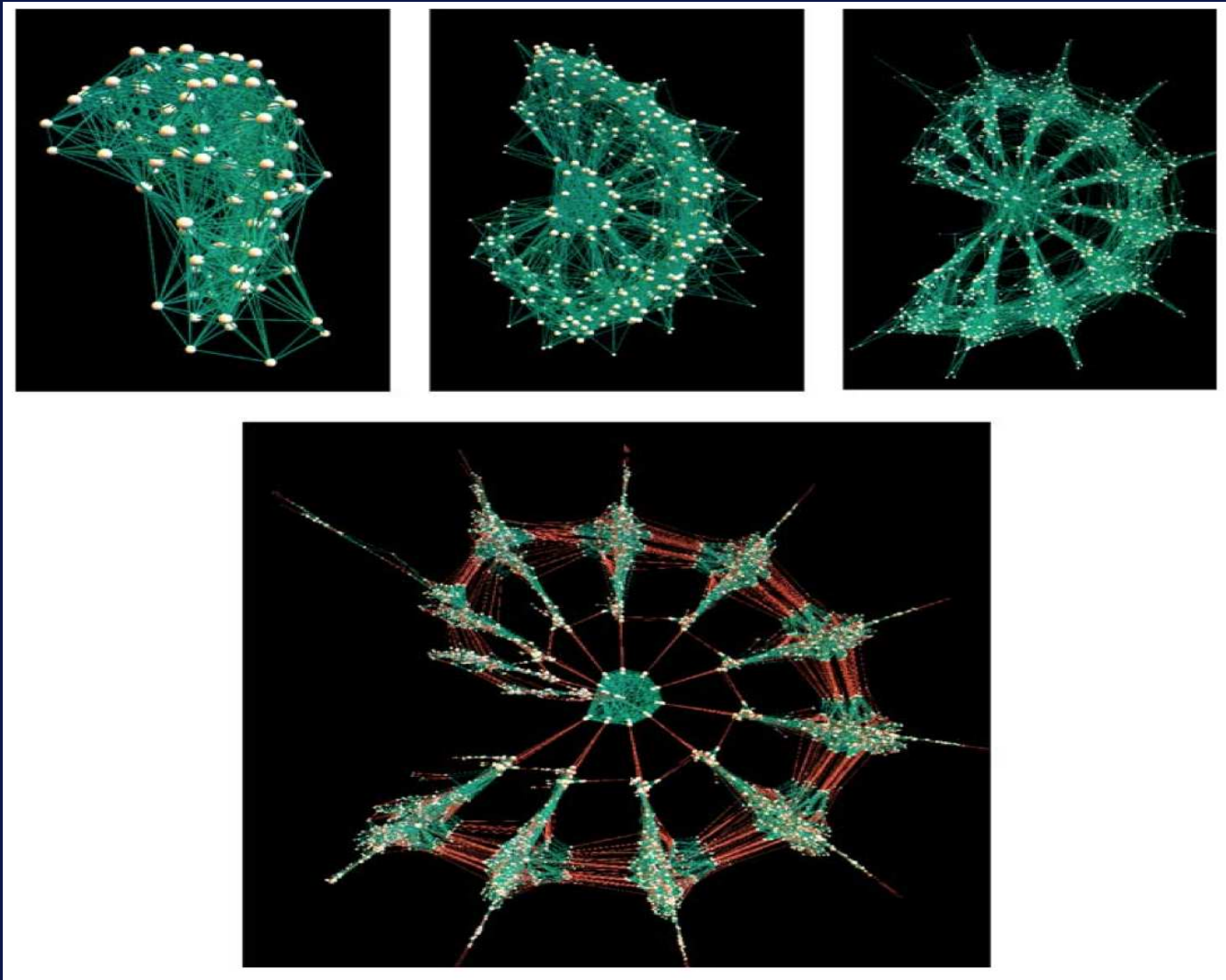


Figure 3: Clause-Based Renderings^[5]

References

- [1] Cook, S. A. (1971). “**The complexity of theorem-proving procedures**”. Proceedings of the 3rd Annual ACM Symposium on Theory of Computing: 151-158.
- [2] Davis, Martin and Putnam, Hilary (1960). “**A Computing Procedure for Quantification Theory**”. Journal of the ACM 7 (3): 201-215.
- [3] Davis, M.; Logemann, G.; Loveland, D. (1962). “**A machine program for theorem-proving**”. Communications of the ACM 5 (7): 394-397.
- [4] Sinz, Carsten. “**Visualizing the internal structure of SAT instances (preliminary report)**”. SAT. Citeseer, 2004.
- [5] Sinz, Carsten. “**Visualizing SAT instances and runs of the DPLL algorithm**”. Journal of Automated Reasoning (Vol. 39 Num. 2): 219-243. Springer, 2007.